

# Power System Elements

## System Loads



**LOADING...**

**PJM State & Member Training Dept.**

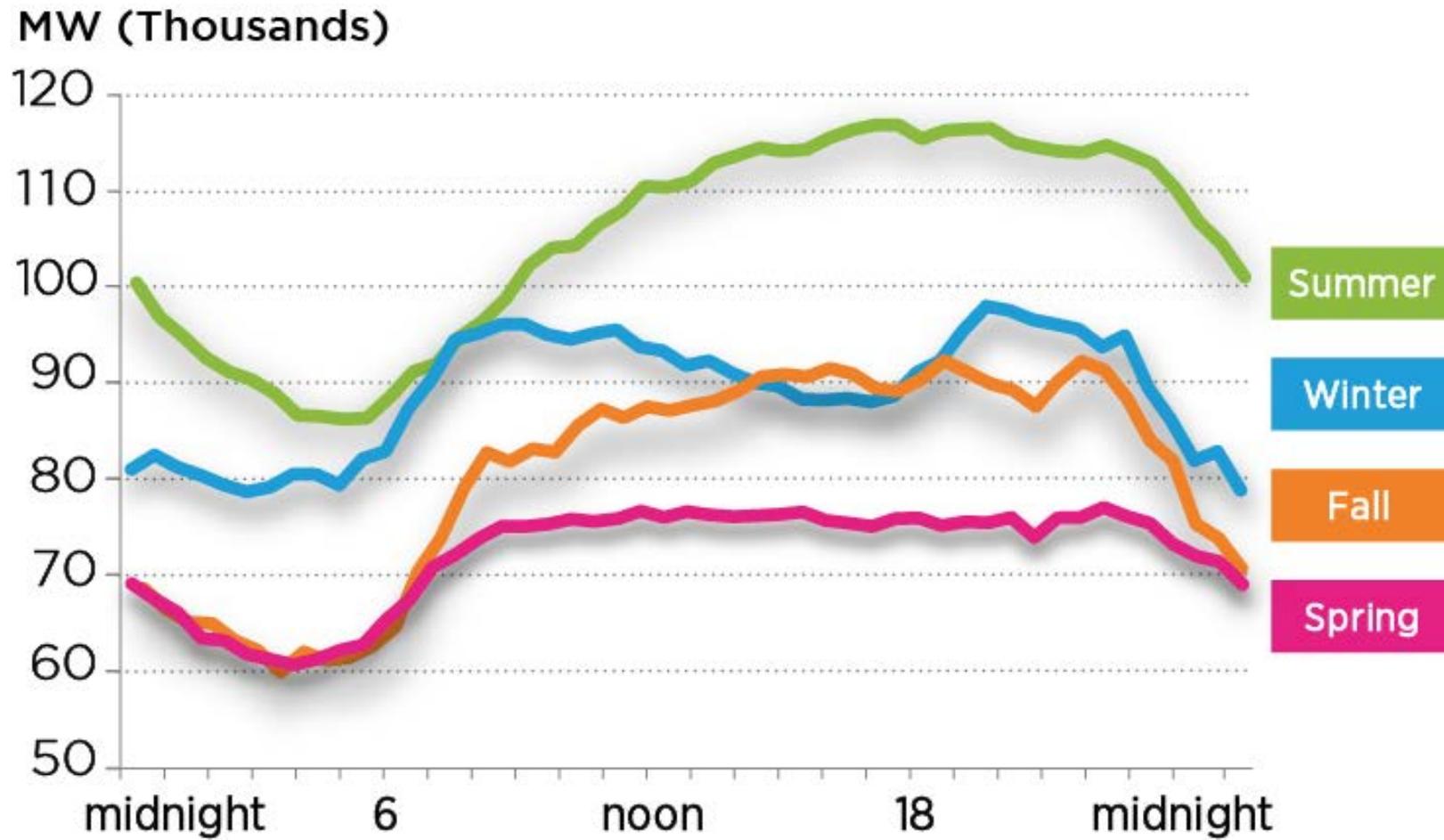
# Objectives



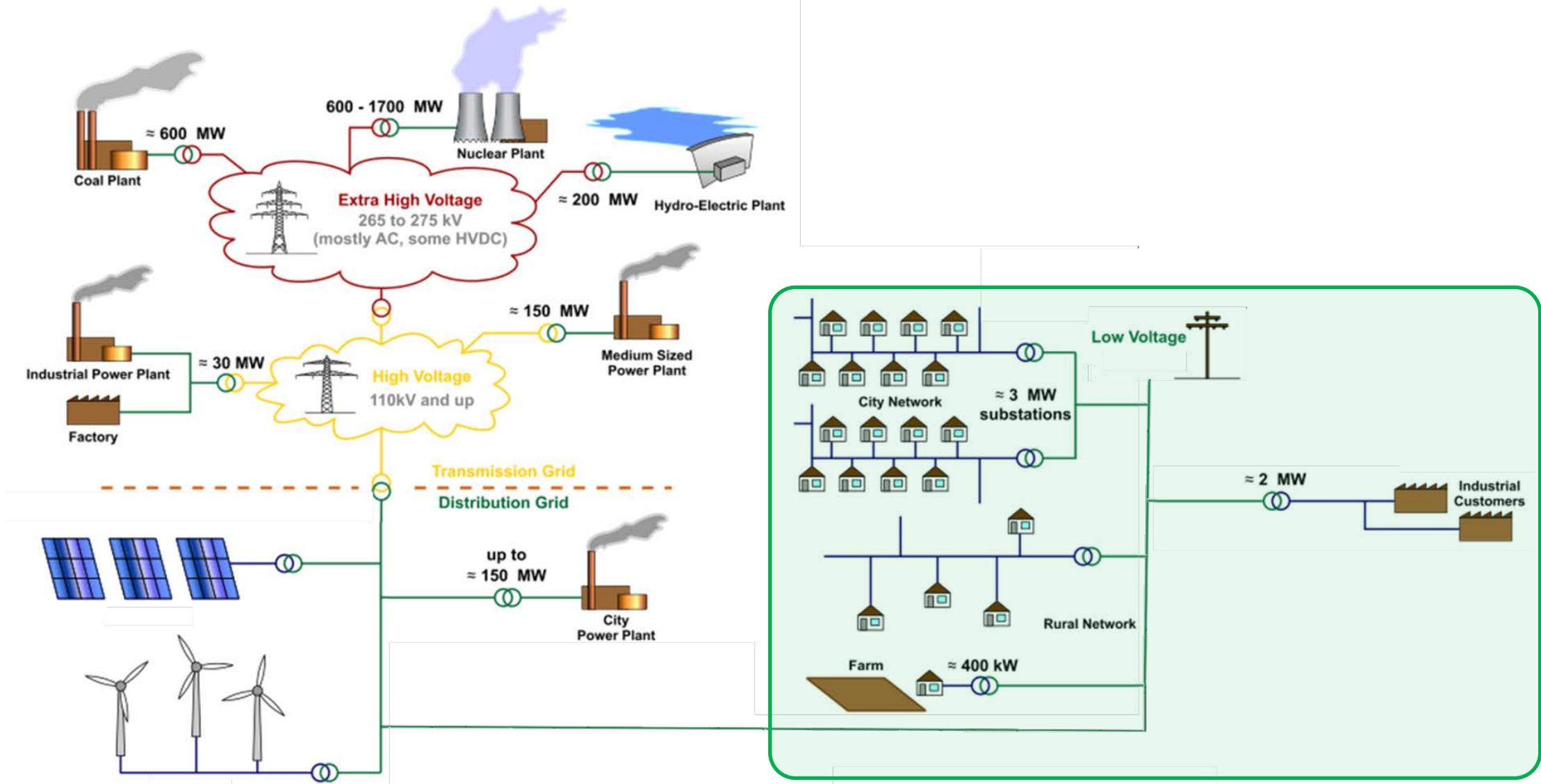
Identify the different types of general load on the power system

- Describe the characteristics of non-motor load on the power system
- Describe the characteristics of the motor loads on the power system
- Describe the effects of changing voltage has on the different load types

# Load Curves

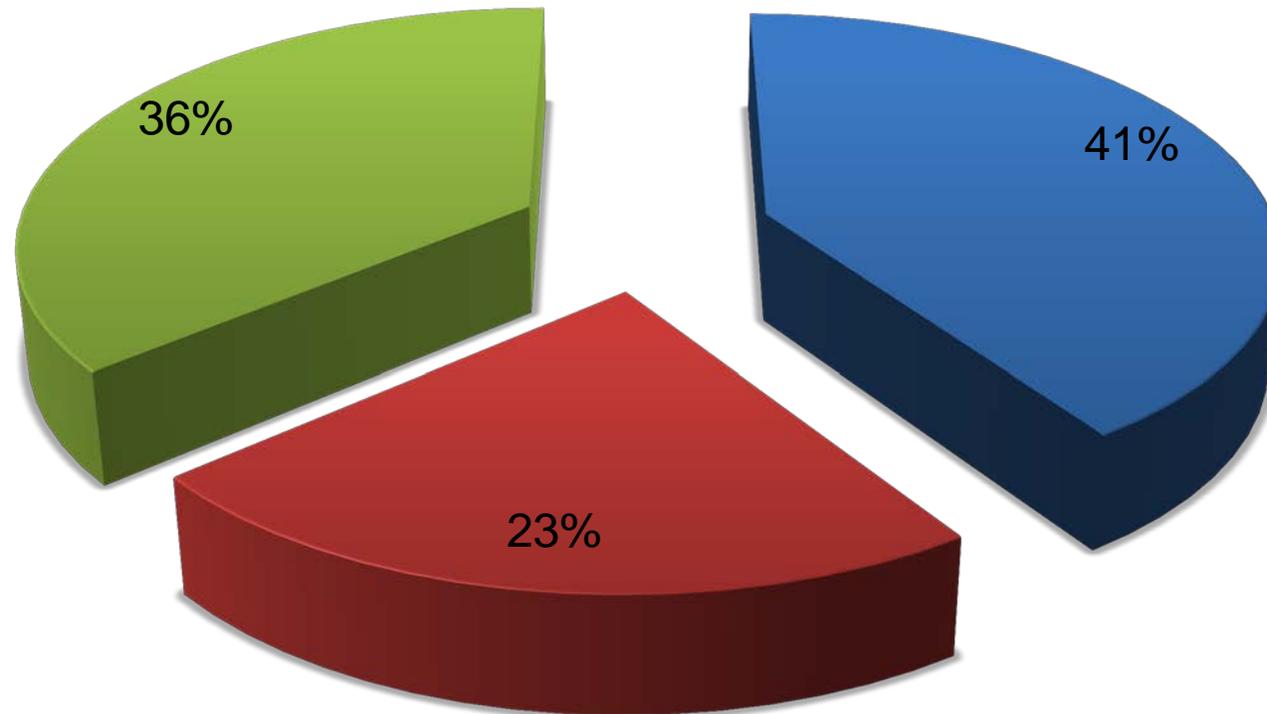


# System Configuration



## PJM's Load Profile\*

■ Residential ■ Industrial ■ Commercial



\*load profile is the average across the RTO as of 2014

# General Types of System Loads

- **Non-Motor**

- Lighting
  - Incandescent, fluorescent, etc.
- Heating
  - Water heating, resistance heating. etc.

# Non-Motor Load

Load magnitude varies with voltage magnitude

- Two general classifications

- 1. Constant Current Load**

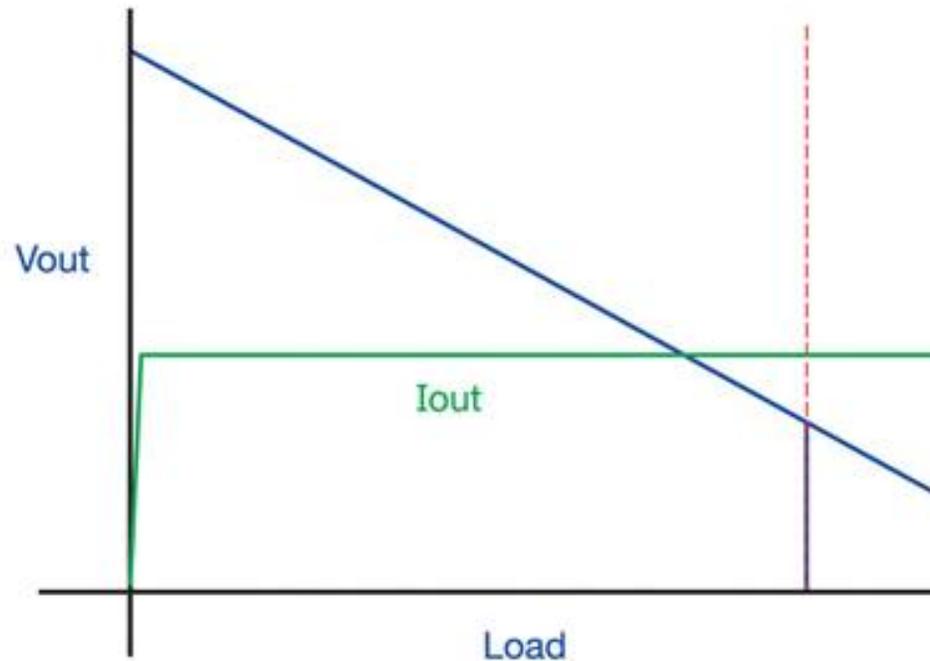
- Varies directly with the voltage

- 2. Constant Resistance/Impedance Load**

- Varies with the square of the voltage

# Non-Motor Load – Constant Current Load

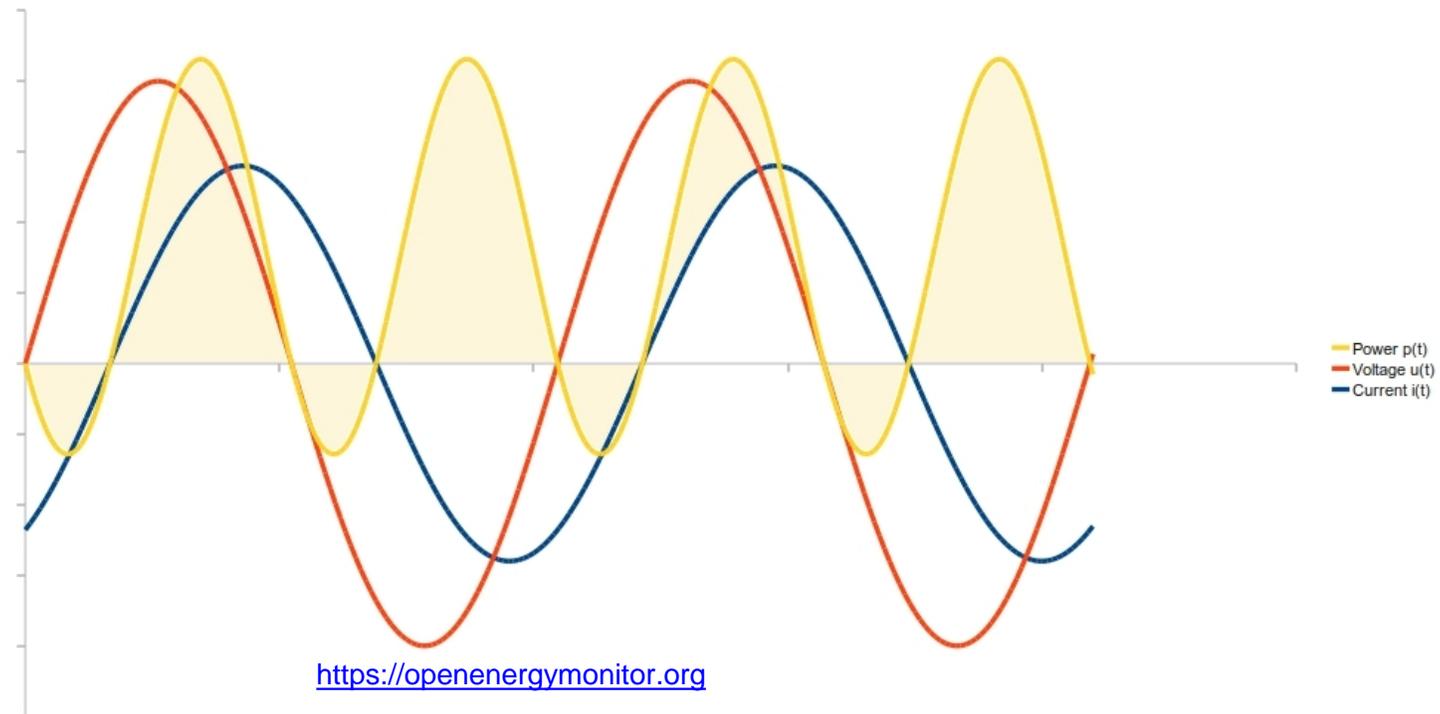
- Current remains constant with fluctuations in voltage so Power is variable
- This is a very rare load on the system
  - Custom designed circuitry for loads that require a constant current



<http://www.digikey.com/>

# Non-Motor Load – Constant Resistance/Impedance Load

- Impedance remains constant as current or voltage changes
- Most non-motor loads on the system appear as constant impedance
  - However every load has slightly different characteristics



# General Types of System Loads

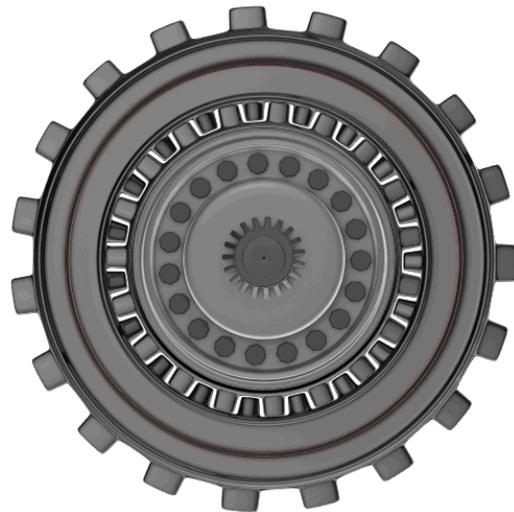
- **Motors**

- Induction

- Most popular type

- Air Conditioners, freezers, washers, fans, pumps, etc.

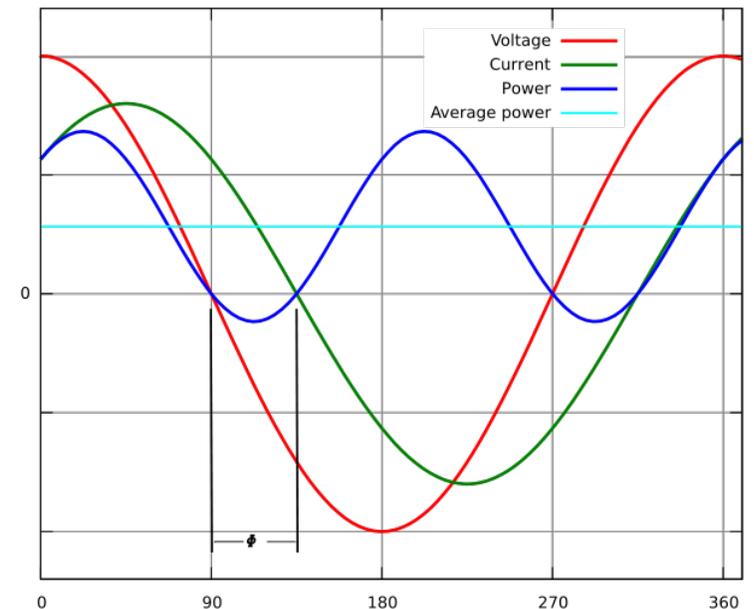
- Synchronous



# Motor Load

Motor Load – makes up a large portion of total load  
**(typically 40% to 60%)**

- Classified as **Constant Power Load**
- Often motors are of the induction type
- Favored due to simplicity and ruggedness
- Requires large amount of reactive power to start



<http://www.overunityresearch.com>

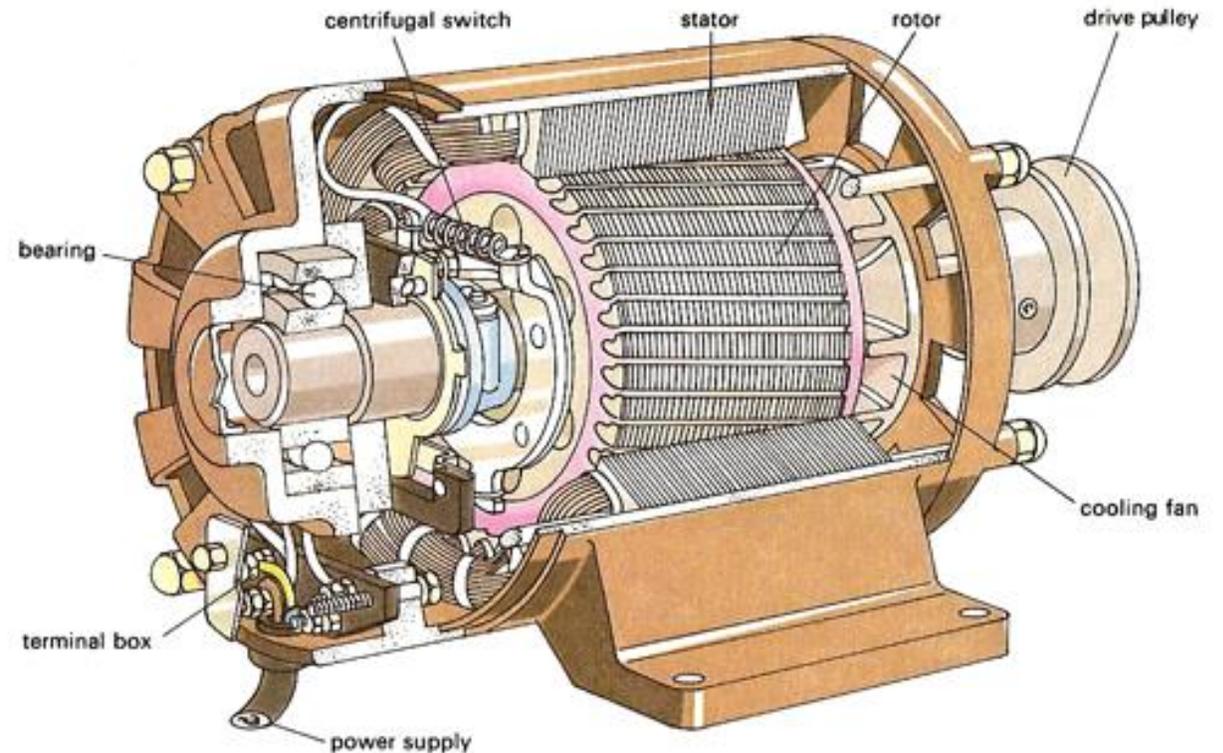
# Motors

- Stator windings are distributed around the stator
- Three-phase AC voltages are applied to the stator windings
- An electric current is induced in the rotor bars
- Magnetic field of the stator drags the rotor around
- Rotor falls behind or “slips” as the field rotates

[Induction Motor Video](#)

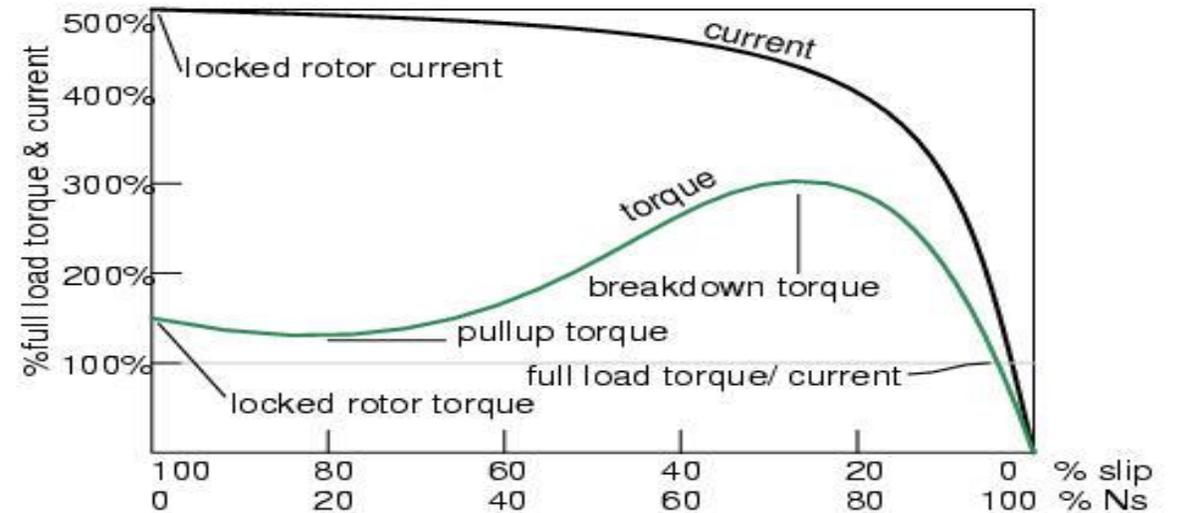
# Motors

- The rotor slots on a squirrel cage rotor are not exactly parallel to the shaft. They are skewed for two main reasons:
  - To make the motor run quietly by reducing magnetic hum
  - To help reduce the locking tendency of the rotor
- Almost 90% of three-phase AC induction motors are of the squirrel cage rotor type



# Characteristics of Motors

- Induction motors at rest appear just like a short circuited transformer
- Draws a very high current called **“Locked Rotor Current” (LRC)** when started
- The LRC of a motor can be as high as 500% of full load current (FLC)



# Characteristics of Motors

The current drawn by a motor has two components:

1. **Reactive (magnetizing current)** – dependent on stator voltage
  - Can vary from as low as 20% of FLC to as high as 60% of FLC
2. **Active (working current)** – directly proportional to the load

# Characteristics of Motors

- Motor load does not significantly vary with voltage magnitude
  - Tries to maintain the same power output as voltage drops
- If voltage drops to 80% or less of rated there is a chance motors will slow down or “stall”
- Combined reactive power draw of numerous stalled motors could prevent system voltage from recovering

# Effect of Frequency on Load

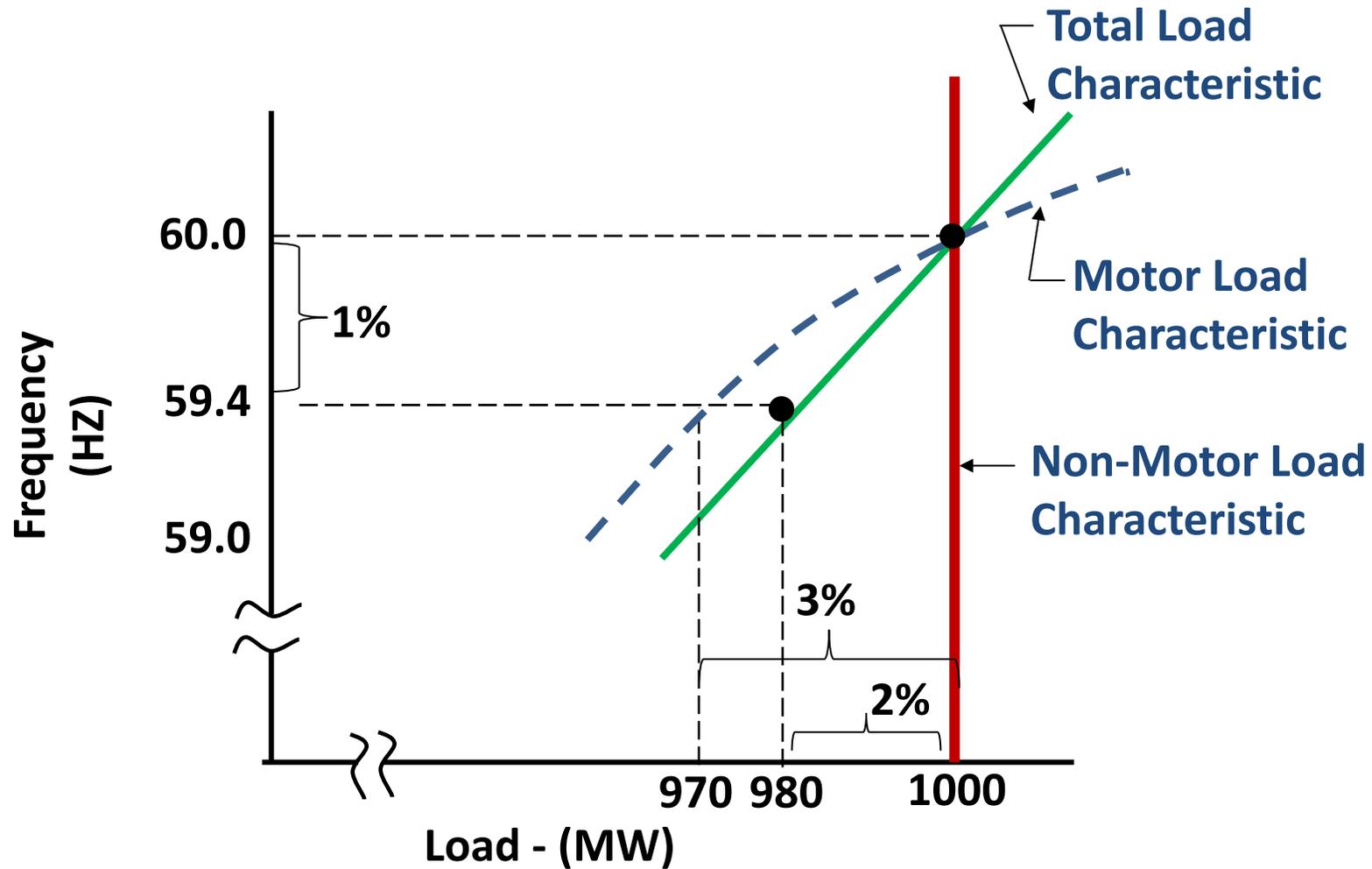
- **Non-Motor Load**

- More dependent on voltage than frequency
- For all intensive purposes we could say that non-motor load does not vary with frequency

- **Motor Load**

- More dependent on frequency than voltage
- Rule of thumb is for a 1% drop in frequency, motor load will decrease by 3%

# Effect of Frequency on Load

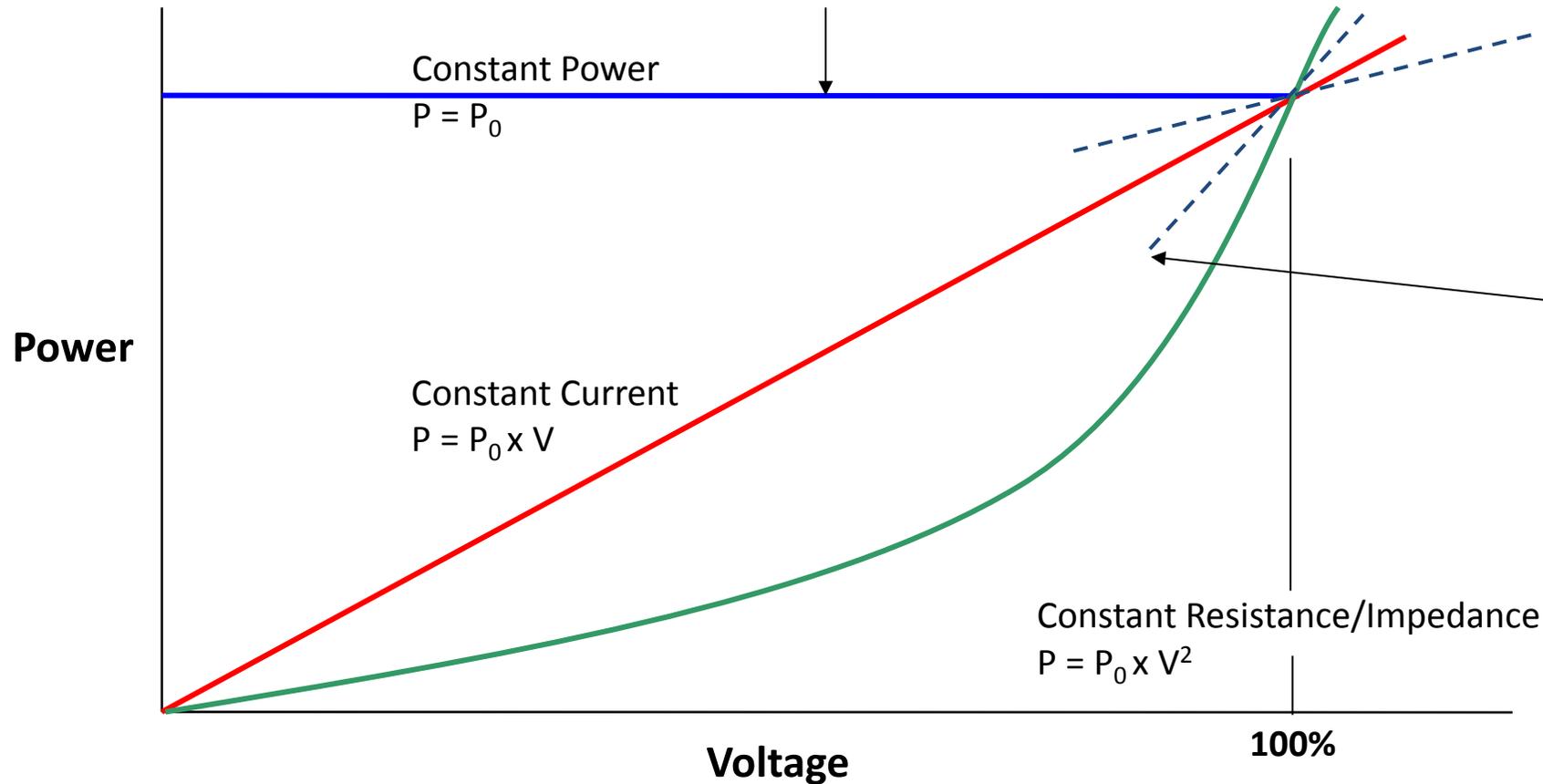


# Effect of Voltage on Loads

**Industrial Load:**  
mostly motors

**Commercial Load:**  
some motors, lots of  
fluorescent lighting,  
computers, cooking  
& miscellaneous

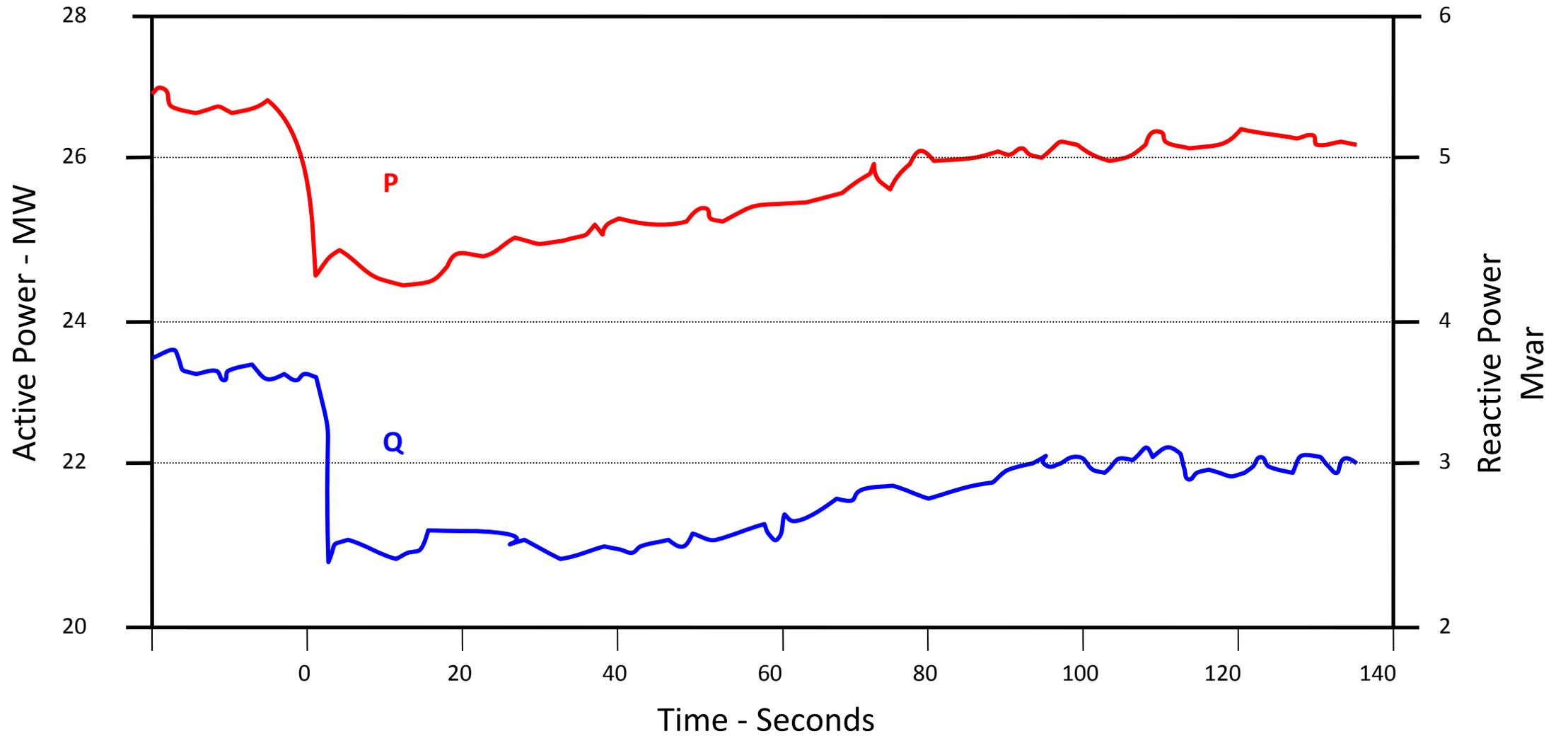
**Residential Load:**  
smaller motors, some  
fluorescent lighting,  
incandescent lighting,  
some heating,  
miscellaneous



# Effect of Voltage on Loads

- Total System Load reduction due to a decrease in voltage
  - A rule of thumb is that for a **5% percent reduction in voltage** you will see approximately a **3% reduction in system load**

# Effect of Time on Load Magnitude



# Load Diversity

- Prolonged periods of low voltage will lead to loss of load diversity
  - During low voltage the output of a heater will reduce
  - This causes more heating units to be on or stay on longer to maintain the same temperature
  - More heaters operating and for longer periods will eventually cause an increase in total system load

# Summary - Load

- Two types of system load are Motor and Non-motor
- Non-motor load has two classifications: Constant current and constant resistance/impedance
- Non-motor load tends to vary with voltage
- Motor load tends to remain constant (Constant Power)
- At start up or when recovering from a stall, motors can draw 5 to 8 times their normal MVARs

# Summary - Load

- Motor load attempting to return from a stalled condition can prevent system voltages from recovering
- Extended periods of low voltage can lead to loss of load diversity
- Loss of load diversity results in an increase of system load
- For a mix of motor and non-motor load, the total customer load on the system will decrease by 3% for a 5% drop in voltage

# Questions?

**PJM Client Management & Services**

**Telephone: (610) 666-8980**

**Toll Free Telephone: (866) 400-8980**

**Website: [www.pjm.com](http://www.pjm.com)**

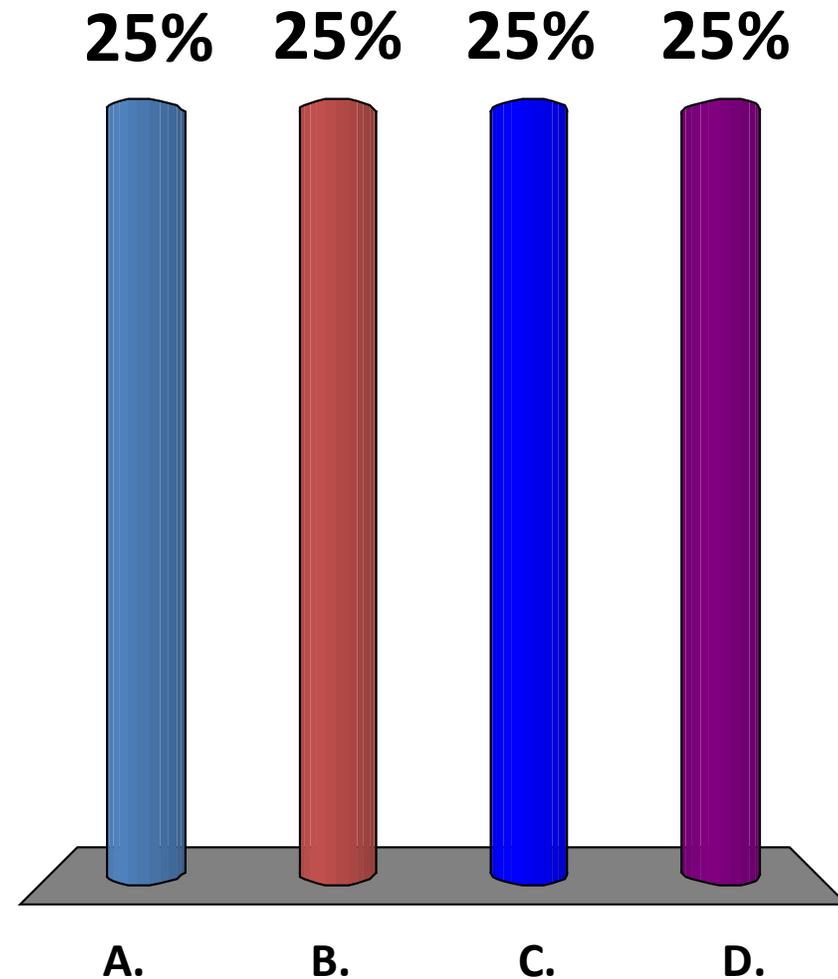


**The Member Community is PJM's self-service portal for members to search for answers to their questions or to track and/or open cases with Client Management & Services**

# What are the 3 classifications of load on the system?

- ✓ A. Constant Power
- ✓ B. Constant Resistance
- ✓ C. Constant Current
- D. Constant Voltage

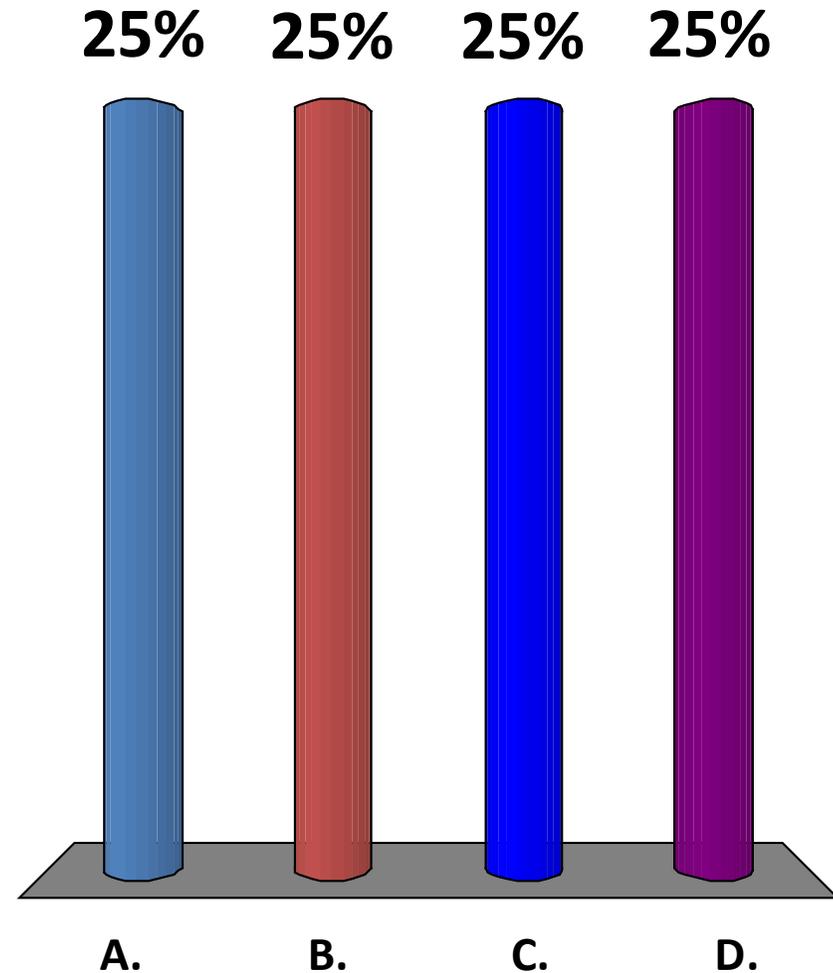
Response Counter



# The two components of current drawn by a motor are Active current and \_\_\_\_\_ current?

- A. Passive
- ✓ B. Reactive
- C. Inrush
- D. Thrust

Response Counter

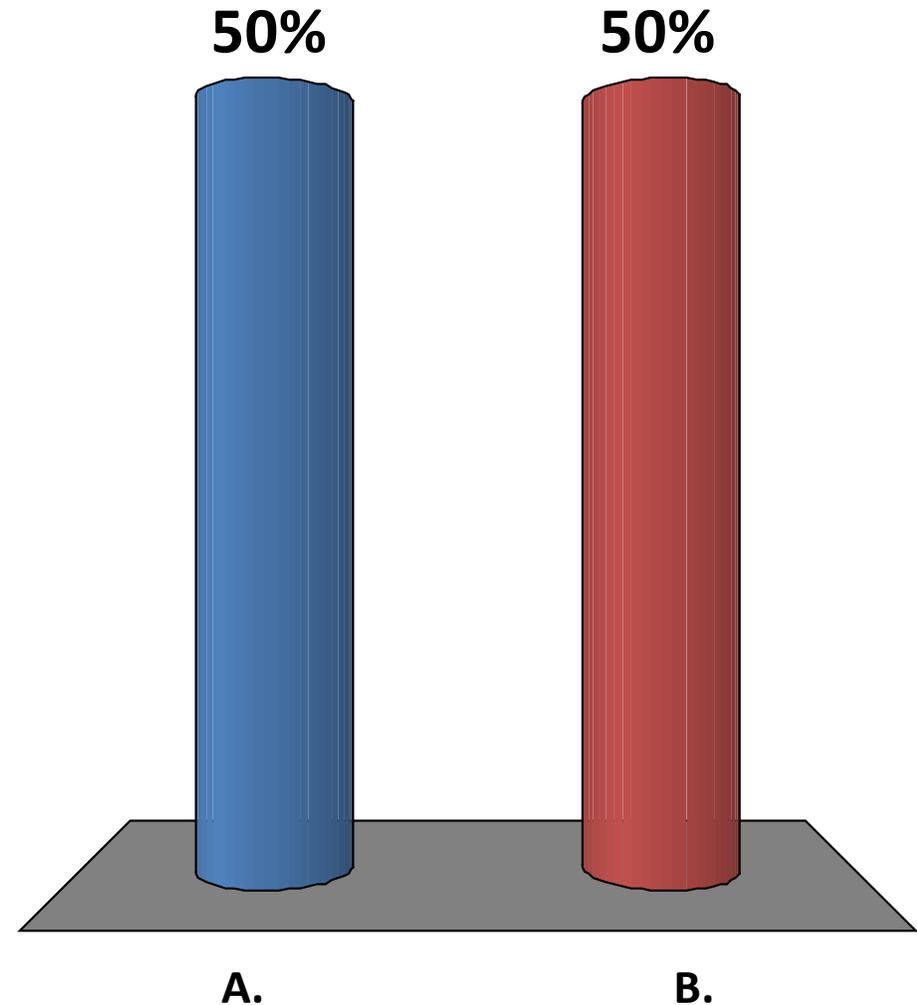


# Both motor and non-motor loads vary with voltage

A. True

✓ B. False

Response  
Counter



**As a rule of thumb, total system load will reduce by \_\_\_ for a 5% drop in voltage**

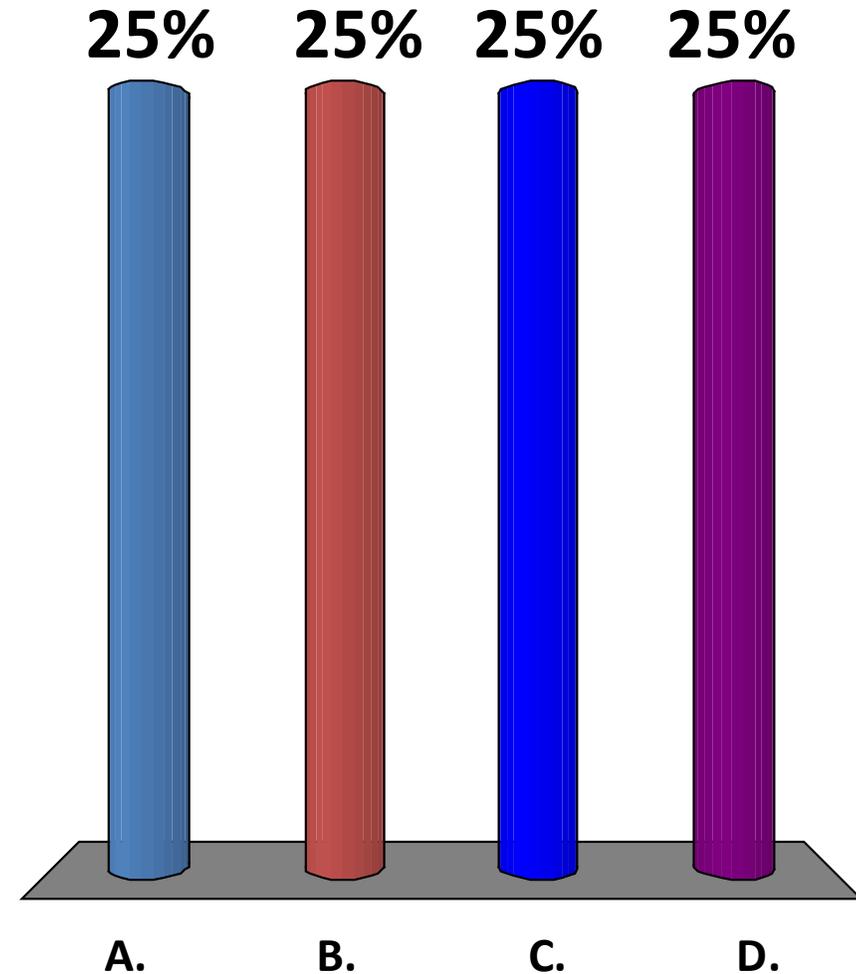
A. 1%

B. 2%

✓ C. 3%

D. 4%

Response  
Counter

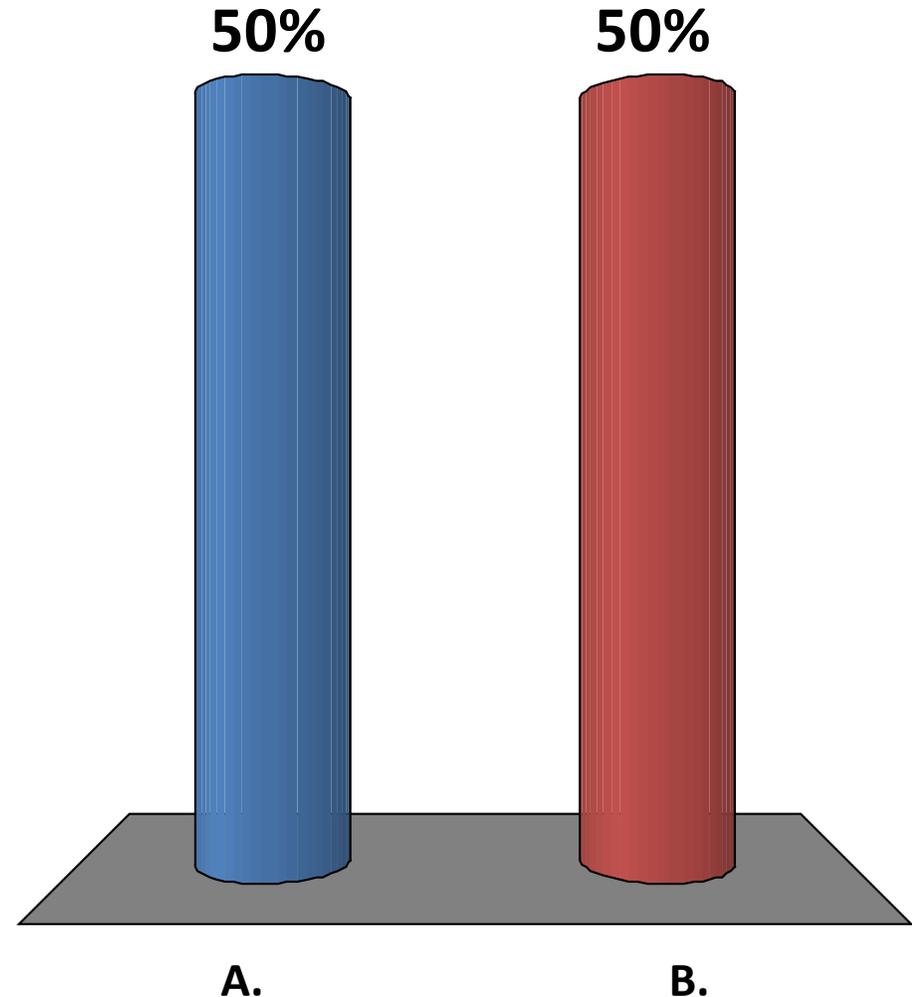


# After a voltage reduction, load remains depressed until the voltage is returned to normal

A. True

✓ B. False

Response Counter



# Resources and References

- Clark, H. (2004). *Voltage and Reactive Power for Planning and Operation*.
- Freescale. (2004-2013). *Motor Control Tutorial*. Retrieved from [http://www.freescale.com/webapp/sps/site/training\\_information.jsp?code=WBT\\_MOTORCONTROL\\_TUT#](http://www.freescale.com/webapp/sps/site/training_information.jsp?code=WBT_MOTORCONTROL_TUT#)